

# FSK Demodulator / Tone Decoder

## GENERAL DESCRIPTION

The XR-2211 is a monolithic phase-locked loop (PLL) system especially designed for data communications. It is particularly well suited for FSK modem applications. It operates over a wide supply voltage range of 4.5 to 20 V and a wide frequency range of 0.01 Hz to 300 kHz. It can accommodate analog signals between 2 mV and 3 V, and can interface with conventional DTL, TTL, and ECL logic families. The circuit consists of a basic PLL for tracking an input signal within the pass band, a quadrature phase detector which provides carrier detection, and an FSK voltage comparator which provides FSK demodulation. External components are used to independently set center frequency, bandwidth, and output delay. An internal voltage reference proportional to the power supply provides ratio metric operation for low system performance variations with power supply changes.

The XR-2211 is available in 14 pin DTL ceramic or plastic packages specified for commercial or military temperature ranges.

## FEATURES

Wide Frequency Range	0.01 Hz to 300 kHz
Wide Supply Voltage Range	4.5 V to 20 V
DTL/TTL/ECL Logic Compatibility	
FSK Demodulation, with Carrier Detection	
Wide Dynamic Range	2 mV to 3 V rms
Adjustable Tracking Range ( $\pm 1\%$ to $\pm 80\%$ )	
Excellent Temp. Stability	20 ppm/ $^{\circ}\text{C}$ , typ.

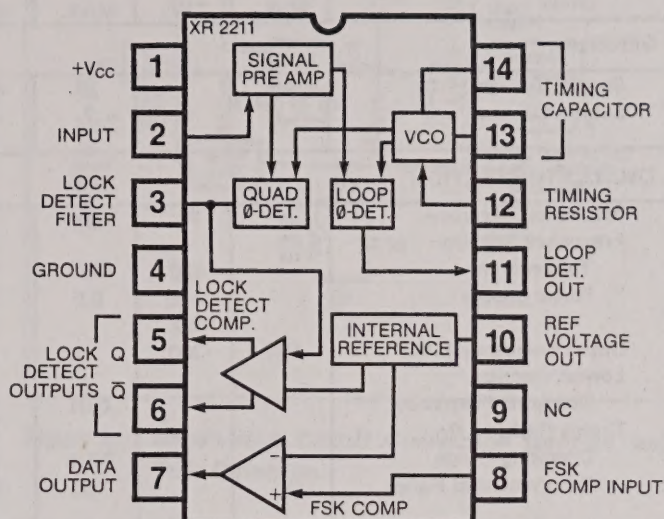
## APPLICATIONS

FSK Demodulation  
Data Synchronization  
Tone Decoding  
FM Detection  
Carrier Detection

## ABSOLUTE MAXIMUM RATINGS

Power Supply	20 V
Input Signal Level	3 V rms
Power Dissipation	
Ceramic Package	750 mW
Derate above $T_A = +25^{\circ}\text{C}$	6 mW/ $^{\circ}\text{C}$
Plastic Package	625 mW
Derate above $T_A = +25^{\circ}\text{C}$	5.0 mW/ $^{\circ}\text{C}$

## FUNCTIONAL BLOCK DIAGRAM



## ORDERING INFORMATION

Part Number	Package	Operating Temperature
XR-2211M	Ceramic	$-55^{\circ}\text{C}$ to $+125^{\circ}\text{C}$
XR-2211CN	Ceramic	$0^{\circ}\text{C}$ to $+75^{\circ}\text{C}$
XR-2211CP	Plastic	$0^{\circ}\text{C}$ to $+75^{\circ}\text{C}$
XR-2211N	Ceramic	$-40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$
XR-2211P	Plastic	$-40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$

## SYSTEM DESCRIPTION

The main PLL within the XR-2211 is constructed from an input preamplifier, analog multiplier used as a phase detector, and a precision voltage controlled oscillator (VCO). The preamplifier is used as a limiter such that input signals above typically 2MV RMS are amplified to a constant high level signal. The multiplying-type phase detector acts as a digital exclusive or gate. Its output (unfiltered) produces sum and difference frequencies of the input and the VCO output,  $f_{\text{input}} + f_{\text{input}}$  ( $2 f_{\text{input}}$ ) and  $f_{\text{input}} - f_{\text{input}}$  (0 Hz) when the phase detector output to remove the "sum" frequency component while passing the difference (DC) component to drive the VCO. The VCO is actually a current controlled oscillator with its nominal input current ( $f_0$ ) set by a resistor ( $R_0$ ) to ground and its driving current with a resistor ( $R_1$ ) from the phase detector.

The other sections of the XR-2211 act to: determine if the VCO is driven above or below the center frequency (FSK comparator); produced both active high and active low outputs to indicate when the main PLL is in lock (quadrature phase detector and lock detector comparator).



## ELECTRICAL CHARACTERISTICS

**Test Conditions:** Test Circuit of Figure 1,  $V^+ = V^- = 6V$ ,  $T_A = +25^\circ C$ ,  $C = 5000 \text{ pF}$ ,  $R_1 = R_2 = R_3 = R_4 = 20 \text{ K}\Omega$ ,  $R_L = 4.7 \text{ K}\Omega$ , Binary Inputs grounded,  $S_1$  and  $S_2$  closed unless otherwise specified.

PARAMETERS	XR-2211/2211M			XR-2211C			UNITS	CONDITIONS
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.		
GENERAL								
Supply Voltage Supply Current	4.5	4	20 7	4.5	5	20 9	V mA	$R_0 \geq 10 \text{ K}\Omega$ See Fig. 4
OSCILLATOR SECTION								
Frequency Accuracy Frequency Stability Temperature Power Supply		$\pm 1$ $\pm 20$ 0.05	$\pm 3$ $\pm 50$ 0.5		$\pm 1$ $\pm 20$ 0.05		% ppm/ $^{\circ}\text{C}$ %/V	Deviation from $f_0 = 1/R_0 C_0$ $R_1 = \frac{1}{2}$ See Fig. 8. $V^+ = 12 \pm 1 \text{ V}$ . See Fig. 7. $V^+ = 5 \pm 0.5 \text{ V}$ . See Fig. 7.
Upper Frequency Limit Lowest Practical Operating Frequency Timing Resistor, $R_0$ Operating Range Recommended Range	100	300			300		kHz Hz $\text{K}\Omega$ $\text{K}\Omega$	$R_0 = 8.2 \text{ K}\Omega$ , $C_0 = 400 \text{ pF}$ $R_0 = 2 \text{ M}\Omega$ , $C_0 = 50 \mu\text{F}$ See Fig. 5. See Fig. 7 and 8.
LOOP PHASE								
DETECTOR SECTION								
Peak Output Current Output Offset Current Output Impedance Maximum Swing	$\pm 150$	$\pm 200$ $\pm 1$ 1 $\pm 5$	$\pm 300$	$\pm 100$	$\pm 200$ $\pm 2$ 1 $\pm 5$	$\pm 300$	$\mu\text{A}$ $\mu\text{A}$ $\text{M}\Omega$ V	Measured at Pin 11.  Referenced to Pin 10.
QUADRATURE								
PHASE DETECTOR								
Peak Output Current Output Impedance Maximum Swing	100	150 1 11			150 1 11		$\mu\text{A}$ $\text{M}\Omega$ V pp	Measured at Pin 3.
INPUT PREAMP SECTION								
Input Impedance Input Signal Voltage Required to Cause Limiting		20 2			20 2		$\text{K}\Omega$ mV rms	Measured at Pin 2.
VOLTAGE COMPARATOR SECTIONS								
Input Impedance Input Bias Current Voltage Gain Output Voltage Low Output Leakage Current		2 100 70 300 0.01			2 100 70 300 0.01		$\text{M}\Omega$ nA dB mV $\mu\text{A}$	Measured at Pins 3 and 8. $R_L = 5.1 \text{ K}\Omega$ $I_C = 3 \text{ mA}$ $V_O = 12 \text{ V}$
INTERNAL REFERENCE								
Voltage Level Output Impedance	4.9	5.3 100	5.7	4.75	5.3 100	5.85	V $\Omega$	Measured at Pin 10.



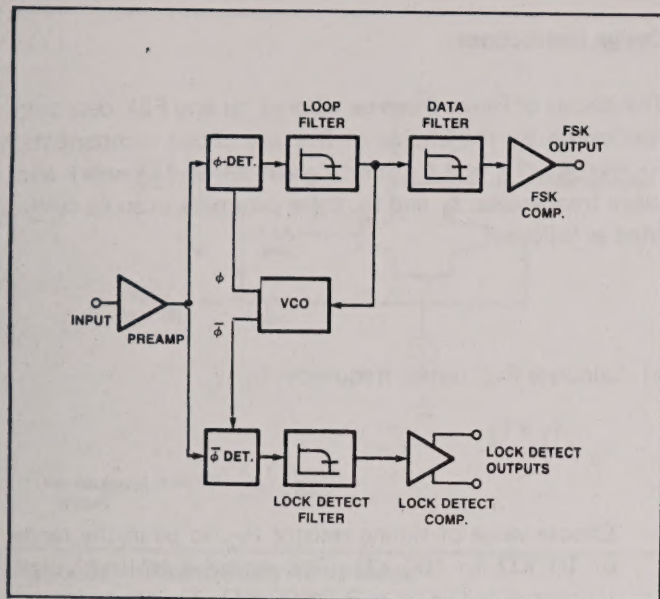


Figure 1: Functional Block Diagram of a Tone and FSK Decoding System Using XR-2211

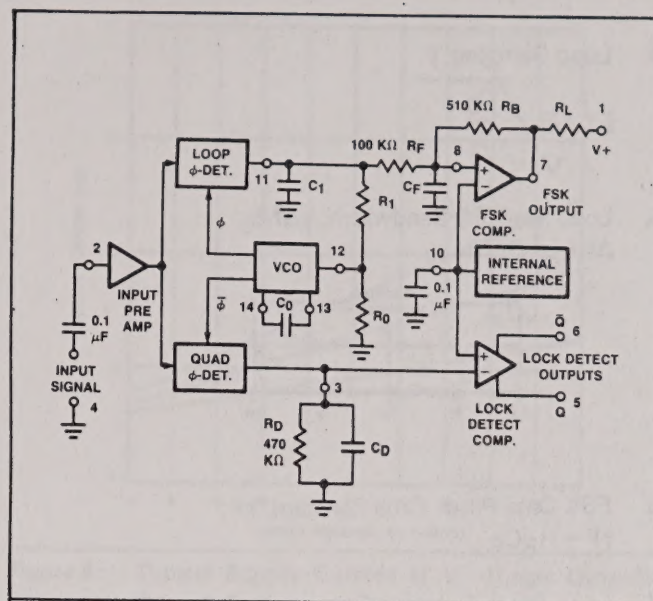


Figure 2: Generalized Circuit Connection for FSK and Tone Detection

**Reference Voltage,  $V_R$**  (Pin 10): This pin is internally biased at the reference voltage level,  $V_R$ :  $V_R = V+/2 - 650$  mV. The dc voltage level at this pin forms an internal reference for the voltage levels at Pins 5, 8, 11 and 12. Pin 10 *must* be bypassed to ground with a  $0.1 \mu\text{F}$  capacitor for proper operation of the circuit.

**Loop Phase Detector Output** (Pin 11): This terminal provides a high impedance output for the loop phase detector. The PLL loop filter is formed by  $R_1$  and  $C_1$  connected to Pin 11 (see Figure 2). With no input signal, or with no phase error within the PLL, the dc level at Pin 11 is very nearly equal to  $V_R$ . The peak voltage swing available at the phase detector output is equal to  $\pm V_R$ .

**VCO Control Input** (Pin 12): VCO free-running frequency is determined by external timing resistor,  $R_0$ , connected from this terminal to ground. The VCO free-running frequency,  $f_0$ , is:

$$f_0 = \frac{1}{R_0 C_0} \text{ Hz}$$

where  $C_0$  is the timing capacitor across Pins 13 and 14. For optimum temperature stability,  $R_0$  must be in the range of  $10 \text{ K}\Omega$  to  $100 \text{ K}\Omega$  see Figure 8).

This terminal is a low impedance point, and is internally biased at a dc level equal to  $V_R$ . The maximum timing current drawn from Pin 12 must be limited to  $\leq 3$  mA for proper operation of the circuit.

**VCO Timing Capacitor** (Pins 13 and 14): VCO frequency is inversely proportional to the external timing capacitor,  $C_0$ , connected across these terminals (see Figure 5).  $C_0$  must be nonpolar, and in the range of  $200 \text{ pF}$  to  $10 \mu\text{F}$ .

**VCO Frequency Adjustment:** VCO can be fine-tuned by connecting a potentiometer,  $R_X$ , in series with  $R_0$  at Pin 12 (see Figure 9).

**VCO Free-Running Frequency,  $f_0$ :** XR-2211 does not have a separate VCO output terminal. Instead, the VCO outputs are internally connected to the phase detector sections of the circuit. However, for set-up or adjustment purposes, VCO free-running frequency can be measured at Pin 3 (with  $C_D$  disconnected), with no input and with Pin 2 shorted to Pin 10.

## DESIGN EQUATIONS

(See Figure 2 for definition of components.)

1. VCO Center Frequency,  $f_0$ :

$$f_0 = 1/R_0 C_0 \text{ Hz}$$

2. Internal Reference Voltage,  $V_R$  (measured at Pin 10):

$$V_R = V+/2 - 650 \text{ mV}$$

3. Loop Low-Pass Filter Time Constant,  $\tau$ :

$$\tau = R_1 C_1$$

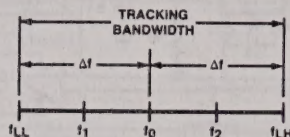


4. Loop Damping,  $\zeta$ :

$$\zeta = 1/4 \sqrt{\frac{C_0}{C_1}}$$

5. Loop Tracking Bandwidth,  $\pm \Delta f/f_0$ :

$$\Delta f/f_0 = R_0/R_1$$



6. FSK Data Filter Time Constant,  $\tau_F$ :

$$\tau_F = R_F C_F$$

7. Loop Phase Detector Conversion Gain,  $K\phi$ : ( $K\phi$  is the differential dc voltage across Pins 10 and 11, per unit of phase error at phase detector input):

$$K\phi = -2V_R/\pi \text{ volts/radian}$$

8. VCO Conversion Gain,  $K_0$ : ( $K_0$  is the amount of change in VCO frequency, per unit of dc voltage change at Pin 11):

$$K_0 = -1/V_R C_0 R_1 \text{ Hz/volt}$$

9. Total Loop Gain,  $K_T$ :

$$K_T = 2\pi K\phi K_0 = 4/C_0 R_1 \text{ rad/sec/volt}$$

10. Peak Phase Detector Current  $I_A$ :

$$I_A = V_R \text{ (volts)}/25 \text{ mA}$$

## APPLICATIONS INFORMATION

### FSK DECODING:

Figure 9 shows the basic circuit connection for FSK decoding. With reference to Figures 2 and 9, the functions of external components are defined as follows:  $R_0$  and  $C_0$  set the PLL center frequency,  $R_1$  sets the system bandwidth, and  $C_1$  sets the loop filter time constant and the loop damping factor.  $C_F$  and  $R_F$  form a one-pole post-detection filter for the FSK data output. The resistor  $R_B$  ( $= 510 \text{ K}\Omega$ ) from Pin 7 to Pin 8 introduces positive feedback across the FSK comparator to facilitate rapid transition between output logic states.

Recommended component values for some of the most commonly used FSK bands are given in Table 1.

### Design Instructions:

The circuit of Figure 9 can be tailored for any FSK decoding application by the choice of five key circuit components:  $R_0$ ,  $R_1$ ,  $C_0$ ,  $C_1$  and  $C_F$ . For a given set of FSK mark and space frequencies,  $f_1$  and  $f_2$ , these parameters can be calculated as follows:

a) Calculate PLL center frequency,  $f_0$ :

$$f_0 = \frac{f_1 + f_2}{2}$$

b) Choose value of timing resistor  $R_0$ , to be in the range of  $10 \text{ K}\Omega$  to  $100 \text{ K}\Omega$ . This choice is arbitrary. The recommended value is  $R_0 \equiv 20 \text{ K}\Omega$ . The final value of  $R_0$  is normally fine-tuned with the series potentiometer,  $R_X$ .

c) Calculate value of  $C_0$  from design equation (1) or from Figure 6:

$$C_0 = 1/R_0 f_0$$

d) Calculate  $R_1$  to give a  $\Delta f$  equal to the mark space deviation:

$$R_1 = R_0 [f_0 / (f_1 - f_2)]$$

e) Calculate  $C_1$  to set loop damping. (See design equation no. 4.):

Normally,  $\zeta \approx 1/2$  is recommended.

Then:  $C_1 = C_0/4$  for  $\zeta = 1/2$

f) Calculate Data Filter Capacitance,  $C_F$ :

For  $R_F = 100 \text{ K}\Omega$ ,  $R_B = 510 \text{ K}\Omega$ , the recommended value of  $C_F$  is:

$$C_F \approx 3/(\text{Baud Rate}) \mu\text{F}$$

Note: All calculated component values except  $R_0$  can be rounded to the nearest standard value, and  $R_0$  can be varied to fine-tune center frequency, through a series potentiometer,  $R_X$ . (See Figure 9.)



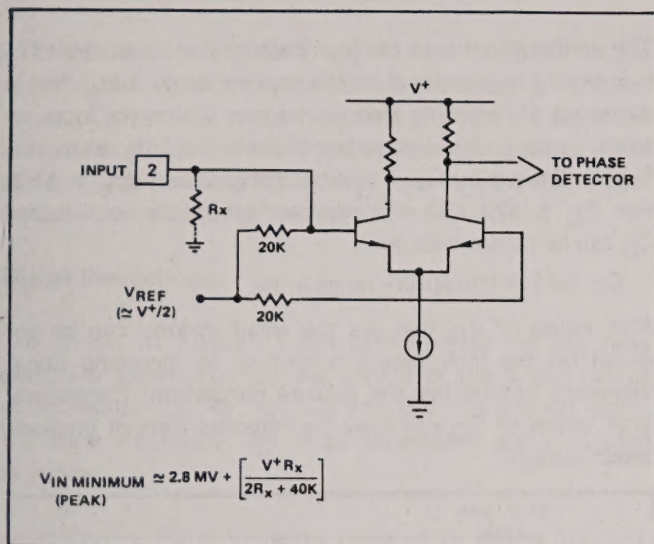


Figure 3: Desensitizing Input Stage

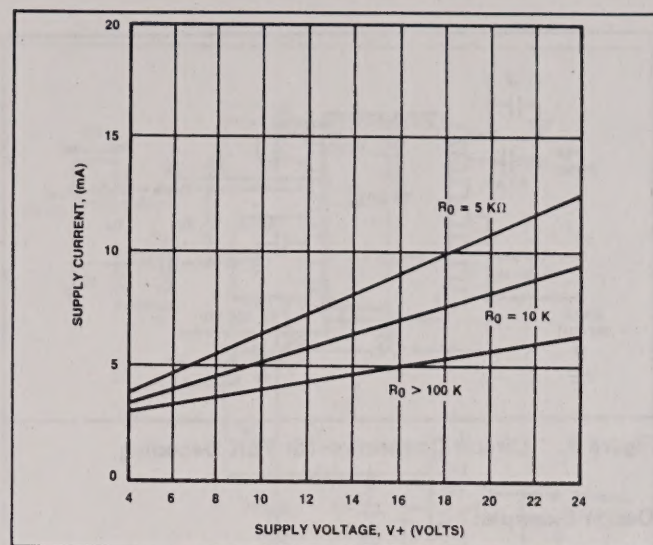


Figure 4: Typical Supply Current vs  $V^+$  (Logic Outputs Open Circuited).

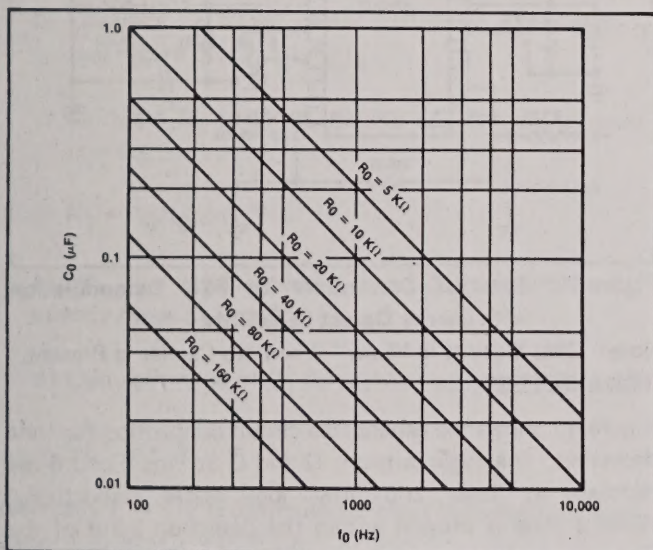


Figure 5: VCO Frequency vs Timing Resistor

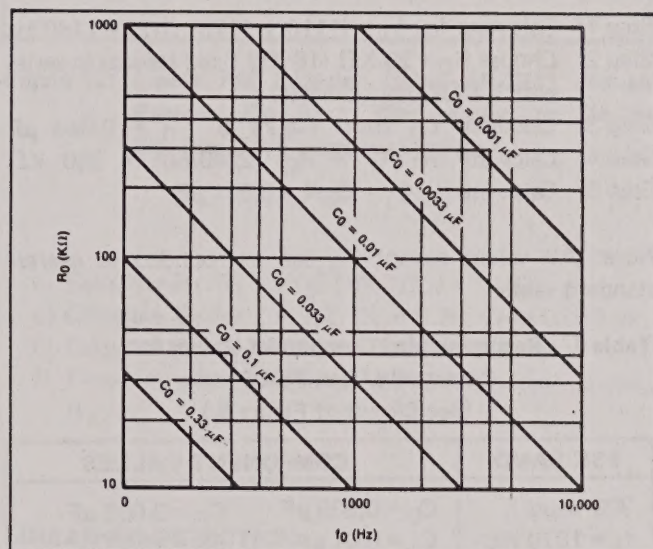


Figure 6: VCO Frequency vs Timing Capacitor

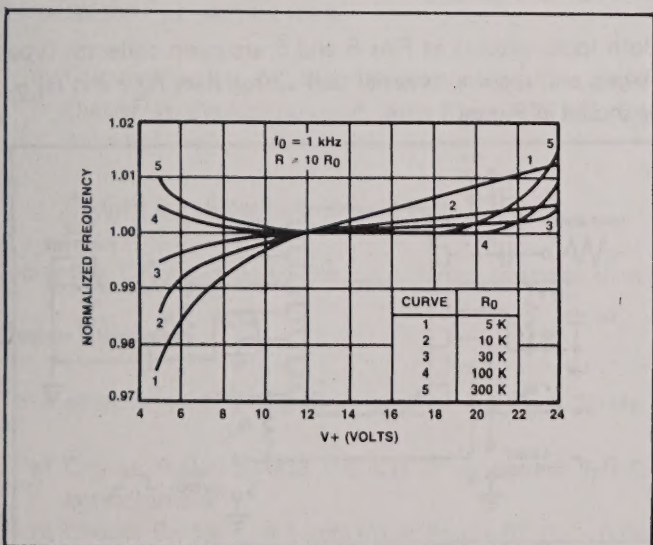


Figure 7: Typical  $f_0$  vs Power Supply Characteristics

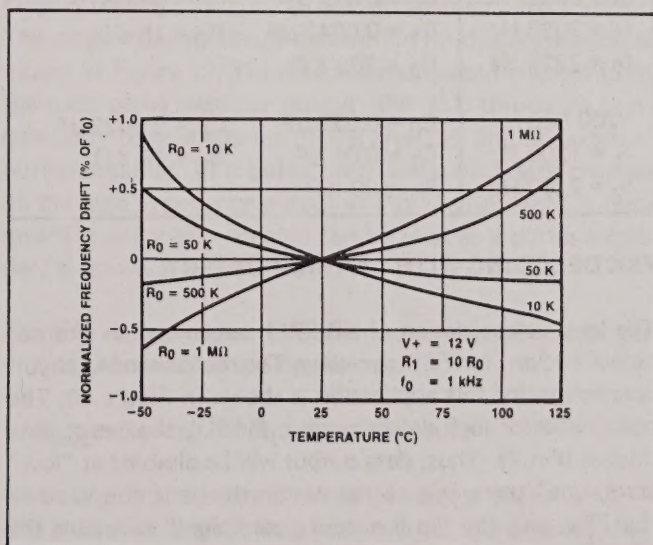
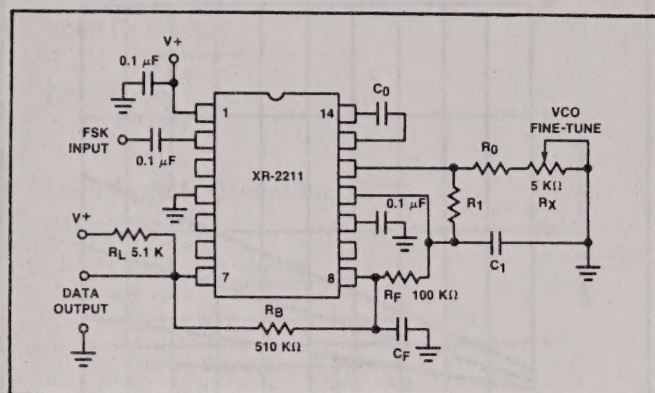


Figure 8: Typical Center Frequency Drift vs Temperature





**Figure 9: Circuit Connection for FSK Decoding**

## Design Example:

75 Baud FSK demodulator with mark space frequencies of 1110/1170 Hz:

Step 1: Calculate  $f_0$ :  $f_0 = (1110 + 1170) (1/2) = 1140$  Hz

Step 2: Choose  $R_0 = 20$  K $\Omega$  (18 K $\Omega$  fixed resistor in series with 5 K $\Omega$  potentiometer)

Step 3: Calculate  $C_0$  from Figure 6:  $C_0 = 0.044$   $\mu$ F

Step 4: Calculate  $R_1$ :  $R_1 = R_0 (2240/60) = 380$  K $\Omega$

Step 5: Calculate  $C_1$ :  $C_1 = C_0/4 = 0.011$   $\mu$ F

Note: All values except  $R_0$  can be rounded to nearest standard value.

**Table 1. Recommended Component Values for Commonly Used FSK Bands.**  
(See Circuit of Figure 9.)

FSK BAND	COMPONENT VALUES	
300 Baud	$C_0 = 0.039$ $\mu$ F	$C_F = 0.005$ $\mu$ F
$f_1 = 1070$ Hz	$C_1 = 0.01$ $\mu$ F	$R_0 = 18$ K $\Omega$
$f_2 = 1270$ Hz	$R_1 = 100$ K $\Omega$	
300 Baud	$C_0 = 0.022$ $\mu$ F	$C_F = 0.005$ $\mu$ F
$f_1 = 2025$ Hz	$C_1 = 0.0047$ $\mu$ F	$R_0 = 18$ K $\Omega$
$f_2 = 2225$ Hz	$R_1 = 200$ K $\Omega$	
1200 Baud	$C_0 = 0.027$ $\mu$ F	$C_F = 0.0022$ $\mu$ F
$f_1 = 1200$ Hz	$C_1 = 0.01$ $\mu$ F	$R_0 = 18$ K $\Omega$
$f_2 = 2200$ Hz	$R_1 = 30$ K $\Omega$	

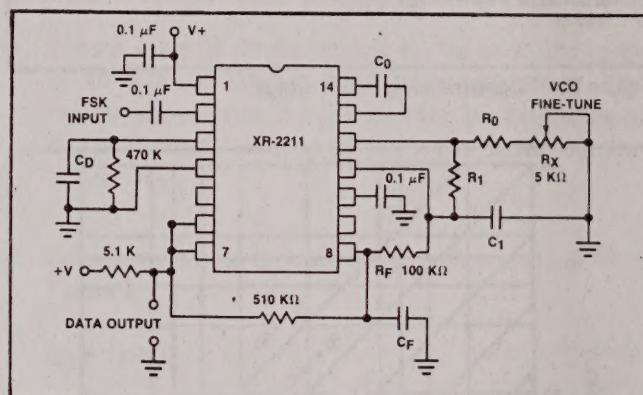
## FSK DECODING WITH CARRIER DETECT:

The lock detect section of XR-2211 can be used as a carrier detect option, for FSK decoding. The recommended circuit connection for this application is shown in Figure 10. The open collector lock detect output, Pin 6, is shorted to "low" state, until there is a carrier within the detection band of the PLL, and the Pin 6 output goes "high," to enable the data output.

The minimum value of the lock detect filter capacitance  $C_D$  is inversely proportional to the capture range,  $\pm\Delta f_c$ . This is the range of incoming frequencies over which the loop can acquire lock and is always less than the tracking range. It is further limited by  $C_1$ . For most applications,  $\Delta f_c > \Delta f/2$ . For  $R_D = 470$  K $\Omega$ , the approximate minimum value of  $C_D$  can be determined by:

$$C_D (\mu\text{F}) \geq 16/\text{capture range in Hz.}$$

With values of  $C_D$  that are too small, chatter can be observed on the lock detect output as an incoming signal frequency approaches the capture bandwidth. Excessively large values of  $C_D$  will slow the response time of the lock detect output.

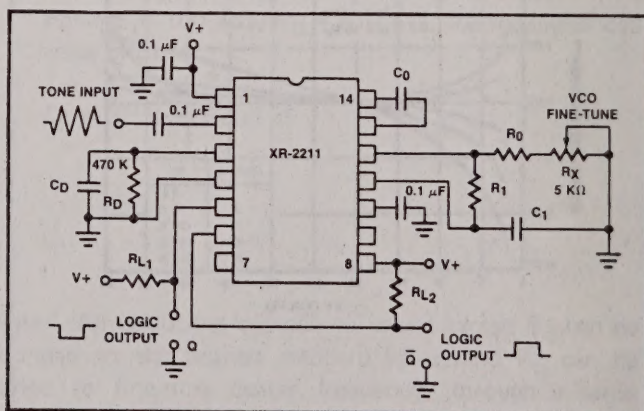


**Figure 10: External Connectors for FSK Demodulation with Carrier Detect Capability**

**Note:** Data Output is "Low" When No Carrier is Present.  
**NOTE DETECTION:**

Figure 11 shows the generalized circuit connection for tone detection. The logic outputs, Q and  $\bar{Q}$  at Pins 5 and 6 are normally at "high" and "low" logic states, respectively. When a tone is present within the detection band of the PLL, the logic state at these outputs become reversed for the duration of the input tone. Each logic output can sink 5 mA of load current.

Both logic outputs at Pins 5 and 6 are open collector type stages, and require external pull-up resistors  $R_{L1}$  and  $R_{L2}$ , as shown in Figure 11.



**Figure 11: Circuit Connection for Tone Detection.**



With reference to Figures 2 and 11, the functions of the external circuit components can be explained as follows:  $R_0$  and  $C_0$  set VCO center frequency;  $R_1$  sets the detection bandwidth;  $C_1$  sets the low pass-loop filter time constant and the loop damping factor.  $R_{L1}$  and  $R_{L2}$  are the respective pull-up resistors for the Q and  $\bar{Q}$  logic outputs.

### Design Instructions:

The circuit of Figure 11 can be optimized for any tone detection application by the choice of the 5 key circuit components:  $R_0$ ,  $R_1$ ,  $C_0$ ,  $C_1$  and  $C_D$ . For a given input, the tone frequency,  $f_S$ , these parameters are calculated as follows:

- Choose  $R_0$  to be in the range of 15 K $\Omega$  to 100 K $\Omega$ . This choice is arbitrary.
- Calculate  $C_0$  to set center frequency,  $f_0$  equal to  $f_S$  (see Figure 6):  $C_0 = 1/R_0 f_S$
- Calculate  $R_1$  to set bandwidth  $\pm \Delta f$  (see design equation no. 5):

$$R_1 = R_0(f_0/\Delta f)$$

Note: The total detection bandwidth covers the frequency range of  $f_0 \pm \Delta f$ .

- Calculate value of  $C_1$  for a given loop damping factor;

$$C_1 = C_0/16\xi^2$$

Normally,  $\xi \approx 1/2$  is optimum for most tone detector applications, giving  $C_1 = 0.25 C_0$ .

Increasing  $C_1$  improves the out-of-band signal rejection, but increases the PLL capture time.

- Calculate value of filter capacitor  $C_D$ . To avoid chatter at the logic output, with  $R_D = 470$  K $\Omega$ ,  $C_D$  must be:

$$C_D(\mu F) \geq (16/\text{capture range in Hz})$$

Increasing  $C_D$  slows down the logic output response time.

### Design Examples:

Tone detector with a detection band of 1 kHz  $\pm$  20 Hz:

- Choose  $R_0 = 20$  K $\Omega$  (18 K $\Omega$  in series with 5 K $\Omega$  potentiometer).
- Choose  $C_0$  for  $f_0 = 1$  kHz (from Figure 6):  $C_0 = 0.05$   $\mu F$ .

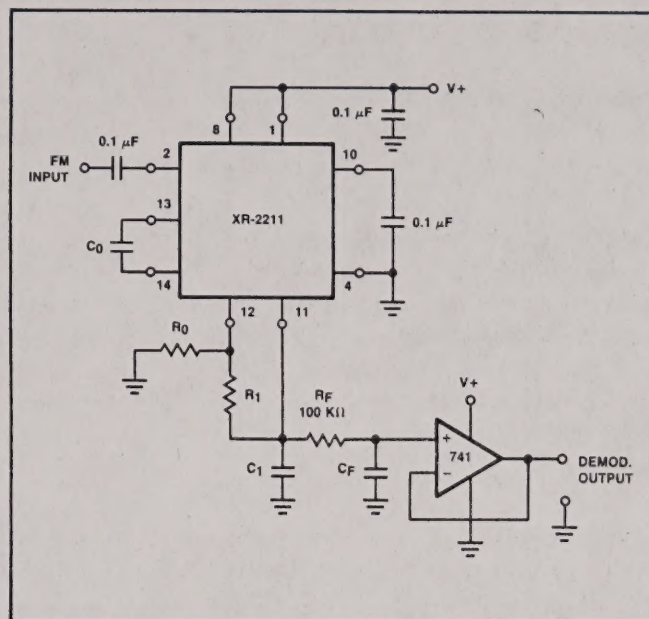


Figure 12: Linear FM Detector Using XR-2211 and an External Op Amp. (See section on Design Equation for Component Values.)

- Calculate  $R_1$ :  $R_1 = (R_0) (1000/20) = 1$  M $\Omega$ .
- Calculate  $C_1$ : for  $\xi = 1/2$ ,  $C_1 = 0.25$ ,  $C_0 = 0.013$   $\mu F$ .
- Calculate  $C_D$ :  $C_D = 16/38 = 0.42$   $\mu F$ .
- Fine-tune center frequency with 5 K $\Omega$  potentiometer,  $R_X$ .

### LINEAR FM DETECTION:

XR-2211 can be used as a linear FM detector for a wide range of analog communications and telemetry applications. The recommended circuit connection for this application is shown in Figure 12. The demodulated output is taken from the loop phase detector output (Pin 11), through a post-detection filter made up of  $R_F$  and  $C_F$ , and an external buffer amplifier. This buffer amplifier is necessary because of the high impedance output at Pin 11. Normally, a non-inverting unity gain op amp can be used as a buffer amplifier, as shown in Figure 12.

The FM detector gain, i.e., the output voltage change per unit of FM deviation can be given as:

$$V_{out} = R_1 V_R / 100 R_0 \text{ Volts/\%deviation}$$

where  $V_R$  is the internal reference voltage ( $V_R = V+/2 - 650$  mV). For the choice of external components  $R_1$ ,  $R_0$ ,  $C_D$ ,  $C_1$  and  $C_F$ , see section on design equations.



## PRINCIPLES OF OPERATION

**Signal Input (Pin 2):** Signal is ac coupled to this terminal. The internal impedance at Pin 2 is 20 K $\Omega$ . Recommended input signal level is in the range of 10 mV rms to 3 V rms.

**Quadrature Phase Detector Output (Pin 3):** This is the high impedance output of quadrature phase detector and is internally connected to the input of lock detect voltage comparator. In tone detection applications, Pin 3 is connected to ground through a parallel combination of  $R_D$  and  $C_D$  (see Figure 2) to eliminate the chatter at lock detect outputs. If the tone detect section is not used, Pin 3 can be left open circuited.

**Lock Detect Output, Q (Pin 5):** The output at Pin 5 is at "high" state when the PLL is out of lock and goes to "low" or conducting state when the PLL is locked. It is an open collector type output and requires a pull-up resistor,  $R_L$ , to  $V_+$  for proper operation. At "low" state, it can sink up to 5 mA of load current.

**Lock Detect Complement,  $\bar{Q}$  (Pin 6):** The output at Pin 6 is the logic complement of the lock detect output at Pin 5. This output is also an open collector type stage which can sink 5 mA of load current at low or "on" state.

**FSK Data Output (Pin 7):** This output is an open collector logic stage which requires a pull-up resistor,  $R_L$ , to  $V_+$  for proper operation. It can sink 5 mA of load current. When decoding FSK signals, FSK data output is at "high" or "off" state for low input frequency, and at "low" or "on" state for high input frequency. If no input signal is present, the logic state at Pin 7 is indeterminate.

**FSK Comparitor Input (Pin 8):** This is the high impedance input to the FSK voltage comparator. Normally, an FSK post-detection or data filter is connected between this terminal and the PLL phase detector output (Pin 11). This data filter is formed by  $R_F$  and  $C_F$  of Figure 2. The threshold voltage of the comparator is set by the internal reference voltage,  $V_R$ , available at Pin 10.

## EQUIVALENT SCHEMATIC DIAGRAM

